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Observation of metre-scale impactors by the Desert Fireball Network

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ABSTRACT

The Earth is impacted by 35–40 metre-scale objects every year. These meteoroids are the low-mass end of impactors that can do damage on the ground. Despite this they are very poorly surveyed and characterized, too infrequent for ground-based fireball observation efforts, and too small to be efficiently detected by NEO telescopic surveys whilst still in interplanetary space. We want to evaluate the suitability of different instruments for characterizing metre-scale impactors and where they come from. We use data collected over the first 3 yr of operation of the continent-scale Desert Fireball Network, and compare results with other published results as well as orbital sensors. We find that although the orbital sensors have the advantage of using the entire planet as collecting area, there are several serious problems with the accuracy of the data, notably the reported velocity vector, which is key to getting an accurate pre-impact orbit and calculating meteorite fall positions. We also outline dynamic range issues that fireball networks face when observing large meteoroid entries.

Key words: meteorites, meteors, meteoroids – minor planets, asteroids: general.

1 INTRODUCTION

The Earth is impacted by 35–40 metre-scale objects every year (Brown et al. 2002; Bland & Artemieva 2006). These large meteoroids are at the low-mass end of potentially damage-causing impacting asteroids like Chelyabinsk (Brown et al. 2013). The study of the atmospheric behaviour, physical nature, numbers, and dynamical origin of these objects is therefore important in order to assess the hazard they pose, and prepare an appropriate response should an asteroid be detected and determined to be on a collision course with Earth.

1.1 How frequently do these impacts happen?

One of the ways the size frequency distribution (SFD) of metre-scale has been surveyed is by using the so-called US Government (USG) sensors, which are able to detect flashes all around the world, day and night, measure flash energy, and sometimes derive velocities and airburst heights. As outlined by Brown et al. (2013), there might be subtleties in the SFD, namely a larger number of 10–50 m objects. Indeed the 1–100 m size range is largely unobserved, with objects too small for telescopes and too infrequent for impact monitoring systems to get representative surveys. So far, there have been three cases of asteroids detected before atmospheric impact. These are

asteroids 2008 TC3 (Jenniskens et al. 2009; Farnocchia et al. 2017), 2014 AA (Farnocchia et al. 2016), and 2018 LA, all discovered by the Catalina Sky Survey only hours before impact. As large deep surveyors like LSST (Ivezic et al. 2008) come online these types of detections are going to become more common, and predicting the consequences of these impacts is going to be desirable. While the impact location of 2008 TC3 was well constrained to sub kilometre precision thanks to a very large number ($\simeq 900$) of astrometric measurements, the prediction for 2014 AA was much more uncertain and covered a large area of the Atlantic ocean, as only a total of seven astrometric positions were available. The impact location of 2018 LA was very uncertain, until two extra observation by the Asteroid Terrestrial-impact Last Alert System (ATLAS) increased the observation arc length from 1.3 to 3.7 h, which narrowed down the impact location to South Africa. The number of astrometric observations and the length of the observation arc are therefore a critical factors to precisely determining the impact point. Well coordinated, large follow-up networks of telescopes can provide large numbers of such observations and will aid in future impact predictions (Lister et al. 2016).

1.2 How dangerous are these impacts?

The damage from an impact depends not only on dynamical parameters, but also on: size, rock type, structure, strength (s), and density (ρ). To illustrate this, we can use the equations of Collins, Melosh & Marcus (2005) to simulate the outcome of the impact of a 2 m object, with an entry angle of 18°, a velocity of 19 km s⁻¹ at the top

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¹https://cneos.jpl.nasa.gov/fireballs/ accessed 2017 November 22.

of the atmosphere (same entry angle and velocity as Chelyabinsk), and various bulk strengths and densities corresponding to different classes of objects (from Chyba, Thomas & Zahnle 1993):

- (i) a weak cometary body ($s = 10^5 \, \text{Pa}$, $\rho = 1000 \, \text{kg m}^{-3}$) will breakup at a high altitude (60 km), causing no significant direct damage because the predicted 0.18 kT TNT of energy released cannot be transferred efficiently to the ground due to the thin atmosphere (1 kT TNT = $4.184 \times 10^{12} \, \text{J}$).
- (ii) a chondritic body ($s = 10^7 \, \text{Pa}$, $\rho = 3500 \, \text{kg m}^{-3}$) is likely going to airburst at relatively low altitudes (the model predicts an airburst at 27 km), releasing around 0.44 kT TNT of energy that can be propagated more efficiently by the denser atmosphere.
- (iii) an iron ($s = 10^8 \, \mathrm{Pa}$, $\rho = 7900 \, \mathrm{kg m^{-3}}$) monolith will reach the surface at hypersonic velocity (3.8 km s⁻¹), causing important but very localized damage, as it only yields $10^{-1} \, \mathrm{kT}$ TNT.

This is a simplistic example, but it shows how much the response to an imminent asteroid impact depends on both physical and dynamical characteristics of the impactor.

Several observation techniques can be levied while the asteroid is still in interplanetary space:

- (i) Multiband photometry in Vis-NIR: size and rotation period, and lower constraint on cohesive strength as a consequence.
 - (ii) Spectroscopy: likely composition.
- (iii) Astrometric observations: pre-encounter orbit, and predictions about the impact geometry, velocity, and location.
- (iv) Radar observations: size, shape, rotation period, presence of satellites.

While the size and impacting velocity are well constrained factors using astrometric observations, determining the rock type and structure from remote sensing instruments is more challenging.

To some extent spectroscopy can provide insights on the mineralogy of the impactor, but this technique requires a good knowledge of how asteroid spectral types match meteorite types.

Another approach is the work of Mommert et al. (2014a, b) on small (metre-scale) asteroids for which spectroscopic work is generally impractical. They used a thermophysical model combined with an orbital model that takes non-gravitational forces into accounts. This model derives physical parameters (likely surface composition, size) by combining both astrometric observations and near-infrared photometry.

In order to be reliable on large scales, these techniques have to be qualified with direct sample analysis. This active area of research can be tackled in two ways: either direct sample return missions (like Stardust, Hayabusa, Hayabusa 2, OSIRIS-REx), or from a large number of meteorite recoveries with associated orbits that can link to asteroid families: the aim of ground-based efforts like the Desert Fireball Network (DFN).

The DFN is a fireball camera network currently operating in the Australian outback, designed for the detection and recovery of meteorite falls with associated orbits. Currently 52 observatories are deployed. On 2015 January 2, a particularly bright fireball was observed over South Australia, large enough to be simultaneously detected by the US government (USG) sensors, and by the DFN, which had just started science operation 2 months before. Another similarly bright event, also observed by both the DFN and the USG sensors, happened on 2017 June 30 over South Australia

Over the 3 million km² that the DFN covers in Australia, the observation of a metre-scale impactor is only expected to happen once every 4–5 yr (Brown et al. 2002), and once every 8–10 yr

during night time when most dedicated fireball networks operate (without considering clear sky conditions). The observation of two such events during the first 3 yr of operation of the DFN, although outside the nominal collecting area, is somewhat lucky with respect to the size frequency distribution numbers of Brown et al. (2002). These two superbolides are described here and add to the small list of metre-scale impactors that have precisely determined trajectories:

- (i) 13 events compiled and discussed by Brown et al. (2016).
- (ii) the 'Romanian' bolide (Borovička et al. 2017).
- (iii) the Dishchii' bikoh meteorite, for which initial trajectory details have been reported by Palotai et al. (2018).
- (iv) the meteorite fall near Crawford Bay in British Columbia (Canada), for which initial trajectory details have been reported by Hildebrand et al. (2018).

1.3 Where do they come from?

The current state of the art for source region model for Near-Earth Objects (NEO) is detailed by Granvik et al. (2018). They report a significant size dependence of NEO origins, which had not been investigated by earlier similar works (Bottke et al. 2002; Binzel et al. 2004; Greenstreet, Ngo & Gladman 2012). Their work covers the absolute magnitude range 17 < H < 25 (corresponds to diameter 1200 > D > 30 m with an S-type albedo of 0.2), providing little insight on the metre-size region (H = 32).

Several outstanding issues show that it is not possible to simply interpolate the characteristics of the population of typical macroscopic meteorite dropper meteoroids (decimetre-scale) and the kilometre-scale well surveyed by telescopes. For instance, LL chondrites make up 8 per cent of meteorite falls, but it is generally thought that 1/3rd of observable near-Earth small body space is made up of LL compatible asteroids (Vernazza et al. 2008). Granvik et al. (2016) show that an unmodelled destructive effect prevents small bodies from stably populating the low perihelion region, further outlying the need to consider body size in the dynamical models.

Brown et al. (2016) are the first to perform a source region analysis on metre-class NEO bodies, using the Bottke et al. (2002) model on USG events. Considering the small number statistics they get intermediate source regions proportion that are comparable to previous works on kilometre-size NEO population (Bottke et al. 2002; Binzel et al. 2004; Greenstreet et al. 2012). However they also argue for a Halley-type comet (HTC) source region, comparable in importance to the Jupiter-family comets (JFC) source. This source has not been identified previously in NEO works, because of a near-complete lack of such objects in asteroid data bases. Their argument is based on three fireball events in the USG data set that have a Tisserand parameter with Jupiter, $T_{\rm J} < 2$: identified as 20150102-133919, 20150107-010559, and 20150311-061859, not associated with a meteor shower. Because the first two of these events have independently estimated trajectories, an issue that we are interested in is determining if this surprising outcome could be the results of limitations of USG data.

This work aims to compile independent information not just for these cases, but for several other metre-scale bodies, to determine the reliability of USG data in general, for population study, orbit determination, as well as undertaking meteorite searches based on these data. We also evaluate the suitability of hardware currently deployed by fireball networks to observe these particularly bright events.

2 DATA AND METHODS

2.1 DFN

The DFN is the world's biggest fireball observation facility (3 million km² coverage), set-up in a desert environment where meteorites are more likely to be successfully recovered. The DFN is built to overcome the challenges of operating a distributed network of high technology devices in a harsh remote environment. The observatories operate completely autonomously for up to two years before maintenance is required: swapping the hard drives and replacing the mechanical shutter in the off-the-shelf camera. The systems can operate with network connectivity for event notifications, or completely offline. Due to their low power usage, simple solar photovoltaic systems ($\approx\!160{-}240\,\mathrm{W}$ of solar panels) with 12 V deep-cycle lead acid battery storage are used to power most of the observatories across the network.

The main imaging system consists of a high-resolution digital camera and a fisheye all-sky lens, taking long exposures with shutter breaks embedded by the GNSS synchronized operation of a liquid crystal shutter. This mode of imaging has historically been the most successful method for determining positions of fallen meteorites from fireball observation, as shown in the compilation of Borovička, Spurný & Brown (2015). The DFN has recovered three meteorites in the first 3 yr of operation (Devillepoix et al. 2018). The automated observatories are more completely described by Howie et al. (2017a), and the encoding method used to record absolute and relative timing (to derive velocity information) is detailed by Howie et al. (2017b).

In 2017 June, the DFN initiated a firmware upgrade across the network to change the time encoding technique on the observatories' microcontroller. These were deployed to all online cameras remotely. The main new feature of this update was a new mode of operation for the liquid crystal shutter, different from the one described by Howie et al. (2017b). This new mode retained the absolute timing encoding through the use of a de Bruijn sequence, but made the pulses much shorter and equal in duration, replacing the 60 ms long dash with two 10 ms pulses and the short 20 ms dash into a single 10 ms pulse, in order to reduce saturation issues on bright fireballs, and make automated centroid determination easier. In Tables 2 and 5 we refer to this new method as pulse-frequency (PF), as opposed to the pulse-width (PW) method of Howie et al. (2017b).

Standard data reductions methods are detailed by Devillepoix et al. (2018). The DFN is optimized to observe macroscopic meteorite dropping events at the low-mass end. The observatories are sensitive to apparent magnitude 0, in order observe a small (\sim 5 cm) meteoroid high enough before significant atmospheric deceleration happens, to derive a precise orbit. But they can also astrometrically observe the brightest phases of ablation of a half-metre size rock (magnitude 15), albeit with saturating the sensor.

Thanks to the large number of stars imaged by the long exposure, the cameras typically achieve their nominal arcmin astrometric precision down to 5° elevations above the horizon (Devillepoix et al. 2018). Typical kilogram scale meteorites usually ablate down to $\sim\!20\,\mathrm{km}$ height, therefore the network is spaced in order to have three camera observation down to this height, which roughly corresponds to a 200 km slant range. Outside of these ideal observation conditions, fireballs are accurately imaged in the high-altitude phase of the flight (useful for orbital calculations), but getting precise meteorite fall positions becomes more difficult due to decreased astrometric precision.

Fireball trajectories are calculated using a modified version of the least-square method of Borovička (1990), and fireball dynamics are analysed using the methods of Sansom et al. (2015) and Gritsevich et al. (2017). Pre-encounter orbits are determined using numerical integration, as described by Jansen-Sturgeon, Sansom & Bland (2018).

The DFN observatories were designed with a low-resolution video system in parallel of the high-resolution still imager, initially as absolute timing device, but later kept on some systems for future daytime observations. These data are too low resolution to provide useful astrometric data, although they can be helpful in getting high temporal resolution photometric data. However the sensor gets saturated when the fireball gets brighter than $m_{\rm V} =$ -5, and the autogain on the cameras can only attenuate the signal by a factor of about four stellar magnitudes. Large fireballs still saturate the sensor, however Devillepoix et al. (2018) have successfully used the sum of all pixels in each field as a proxy for all sky brightness. This method is particularly successful at detecting large fragmentation events. The effect of autogain are corrected by performing traditional photometry on a non-saturated bright star, planet, or fixed light in the field of view. Unfortunately because of the lossy compression of the record and the sensor saturation, it is not possible to get a satisfying absolutely calibrated photometry from the video, and therefore the resulting light curve is only used qualitatively.

2.2 USG sensors

Large fireballs detected by the so-called 'USG sensors' are reported on the JPL website.² These sensors are apparently able to detect flashes all around the world, day and night, measure flash energy, and sometimes derive velocities and airburst heights. These data were used for size-frequency studies of metre-scale objects by Brown et al. (2002), and later to derive orbital and physical properties of this population (Brown et al. 2016).

In Table 1 we give the data for the subset of events for which all the parameters are reported (time, energy, location, velocity), and for which independent observations have been published (references in Table 7). The USG sensors data do not come with uncertainties, therefore we assume the last significant figure represents the precision of the measurement.

We calculate the radiant and pre-entry orbits for these meteoroids, based on USG data, using the numerical method of Jansen-Sturgeon et al. (2018). The various numbers reported in USG data relate to the instant of peak brightness, typically quite deep into the atmosphere. Since we are dealing with metre-scale bodies, we ignore deceleration due to the atmosphere and use a purely gravitational model from that point for calculating the orbit.

The online table converts the total radiated energy measured into an equivalent impact energy using an empirical relation determined by Brown et al. (2002). This total energy estimate, combined with the impacting speed, can be used to derive a photometric mass using the classical kinetic energy relation ($E = \frac{1}{2}mv^2$), and a rough size assuming a density. Only >= 0.1 kT TNT impacts are reported by the USG,³ which roughly corresponds to a 1 m diameter object at typical impact speeds on Earth.

²https://cneos.jpl.nasa.gov/fireballs/accessed 2017 November 22.

³Johnson L. (2017) – SBAG meeting: https://www.lpi.usra.edu/sbag/meetings/jan2017/presentations/Johnson.pdf and remarks at 32 m and answer

Table 1. USG sensors fireball events that have reported velocities, and have been observed independently. Left of the table is from https://cneos.jpl.nasa.gov/fireballs/(accessed 2017 November 22). Apparent radiants and orbits have been calculated (angles are equinox J2000). The number of decimals is not representative of uncertainty. A similar work has been done by Brown et al. (2016) on the six older events in the list, in agreement. Corresponding ground-based observation details of the two highlighted events are presented in this work, references for the other events are in Table

Peak brightness Date/Time UT	Кm	$\frac{V}{\text{km s}^{-1}}$	Λ_x	V_y km s ⁻¹	V_z ECEF	Radiated E. J	Impact E. kT TNT	Latitude °N +	Longitude °E+	$lpha_{ m inf}^{ m o}$	$\delta_{ m inf}$	a au	в	i	3 °	C ·
2018-06-02 16:44:12	28.7	16.9	6.0	- 16.4	3.9	3.8e + 11	0.98	-21.2	23.3	235.0	- 13.3	1.33	0.42	4.4	258.3	71.88
2017-09-05 05:11:27	36.0	14.7	12.7	-6.1	-4.2	3.8e + 10	0.13	49.3	243.1	216.5	16.7	2.06	0.54	3.4	147.2	162.69
2017-06-30 14:26:45	20.0	15.2	10.9	-9.7	4.2	9.4e + 10	0.29	-34.3	134.5	273.6	-16.1	1.24	0.35	3.6	259.7	98.80
2015-01-07 01:05:59	45.5	35.7	-35.4	1.8	4.4	1.4e + 11	0.4	45.7	26.9	119.7	7.1	4.78	0.93	20.7	111.9	106.19
2015-01-02 13:39:19	38.1	18.1	4.5	-14.4	-10.0	2.0e + 10	0.073	-31.1	140.0	53.8	33.5	9.33	06.0	8.0	207.4	281.61
2013-02-15 03:20:33	23.3	18.6	12.8	-13.3	-2.4	3.8e + 14	440.0	54.8	61.1	329.2	7.3	1.71	0.56	4.1	109.7	326.46
2010-02-28 22:24:50	37.0	15.1	-11.7	2.7	-9.1	1.5e + 11	0.44	48.7	21.0	121.7	37.2	2.70	0.65	3.2	204.0	340.14
2008-11-21 00:26:44	28.2	12.9	3.9	-4.1	-11.6	1.4e + 11	0.41	53.1	250.1	200.6	64.0	0.79	0.26	10.4	3.1	239.04
2008-10-07 02:45:45	38.9	13.3	-9.0	0.6	3.8	4.0e + 11	1.0	20.9	31.4	12.4	-16.7	1.65	0.43	3.9	36.2	14.16

3 RESULTS

In this section we analyse in detail the atmospheric entry of two large meteoroids as observed by the DFN, these were also observed by the USG sensors (highlighted rows in Table 1).

3.1 DN150102_01 - Kalabity

On 2015 January 2 a bright bolide lit up the skies over lake Frome in South Australia (Fig. 1), starting at 2015-01-02T13:39:11.086 UTC (9 min after midnight ACDT) for 10.54 s. In early 2015 the DFN had just finished its initial expansion phase in South Australia with 16 cameras, unfortunately the bolide happened outside the standard network covering area at that time. Therefore a combination of cameras mostly over 300 km from the event had to be used to determine the trajectory (Table 2). The best convergence angle is 22° (between Gum Glen and William Creek). The convergence angle between the Billa Kalina and Ingomar stations is less than 1°, therefore the latter distant viewpoint does not help much in constraining the trajectory. The trajectory follows a relatively shallow slope of 20° to the horizon, visible on the images from 83.3 km altitude. Astrometric uncertainties vary between 1.5-3 arcmin (equates to 130-260 m once projected at 300 km). These are obtained by compounding astrometric calibration uncertainties (typically 1 arcmin) and fireball picking uncertainties (usually 0.5-1 pixel, depending on optics quality and fireball brightness). Most of the residuals to the straight line fit (Fig. 2) are then in agreement with astrometric uncertainties. As expected from an unconstrained astrometric solution under 5° elevation, the observation residuals to the straight line fit start diverging for observations below this elevation, this is visible on around the 52 km altitude mark on the Ingomar and William Creek viewpoints.

The all-sky light curves display early fragmentation events under 0.05 and 0.08 MPa and (peaks A and B in Fig. 3). The following part of the light curve is uneventful until the body encounters an order of magnitude higher dynamic pressures that eventually almost entirely destroys it (peaks C to G in Fig. 3). This adds to the list of large meteoroids (Popova et al. 2011) that undergo fragmentation under pressures several orders of magnitude smaller than the surviving material tensile strength on the ground, or pressures required to destroy the body in our case.

We note that the time reported by the USG sensor (2015-01-02T13:39:19 UTC) is in good agreement with the brightest peak (E) in our light curve determined to be $0.6\,\mathrm{s}$ later (Fig. 3 and Table 3). However the reported altitude is $38\,\mathrm{km}$. This does not correspond to our brightest peak E at $40.2\,\mathrm{km}$, but rather to the end of the very bright phase (peak G).

Only six shutter breaks are resolvable on the image after the explosion on the Billa Kalina image, all $<4^{\circ}$ on the horizon. Using the particle filter method of Sansom, Rutten & Bland (2017) on these data, we find that the main mass at this stage was only a couple of kilograms at the most. We are only able to track down to $33.4 \,\mathrm{km}$ at $8.4 \,\mathrm{km} \,\mathrm{s}^{-1}$. We suspect that this main mass is not visible down to ablation speed limit ($\simeq 3 \,\mathrm{km} \,\mathrm{s}^{-1}$), because of a sensitivity issue: at this stage the meteoroid is at a large distance from the observatory ($> 360 \,\mathrm{km}$), observed on an extreme elevation angle ($\simeq 3.5^{\circ}$), and the sky background is unusually bright because of the light from the main explosions (peaks E–G) raising the background. We suspect the reason this feature is not visible on the closer Gum

to questions at 56 m in online talk: https://ac.arc.nasa.gov/p98hreesxa9/, accessed August 24, 2018.

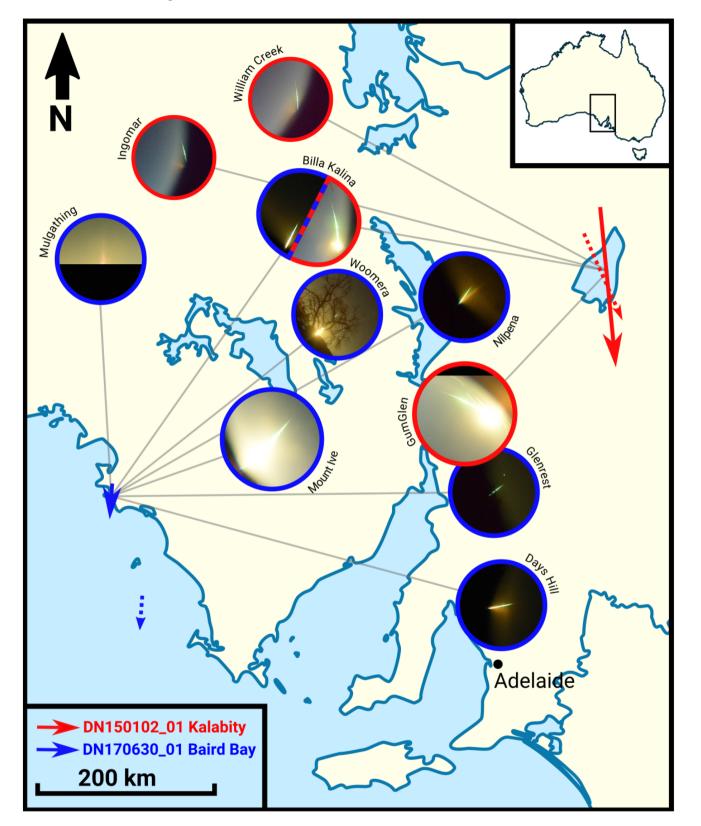


Figure 1. Cropped all-sky images of the fireballs from the DFN observatories. Images are of the same pixel scale with the centre of each image positioned at the observatory location on the map. For the Kalabity fireball (red arrow, East), light from the main explosion is particularly scattered in the Gum Glen image because of clouds. For the Baird Bay event (blue arrow, West), the Mulgathing image is cropped because the sensor is not large enough to accommodate the full image circle on its short side. The fireball on the Woomera picture was partially masked by a tree. The O'Malley station only recorded video and is missing in this map, details are given in Table 5. The dashed arrows show the USG sensors trajectory solutions for both events (vectors are generated by backtracking the state vector at the time of peak brightness to t - 5 s).

Table 2. Locations and nature of instrumental records DN150102_01. P: Photographic record (long exposure high-resolution image), V: compressed PAL video (25 frames per second). PW designates the de Bruijn encoding method, as described in Section 2.1. Ranges are from the fireball at 70 km altitude. Photographic imaging system was out of order for Nilpena.

Observatory	Instruments	Latitude	Longitude	Altitude (m)	Range (km)
Gum Glen – DFNSMALL25	P _{PW} , V	32.20554 S	138.24121 E	242	246
Billa Kalina – DFNSMALL26	P_{PW}	30.23769 S	136.51565 E	114	328
William Creek - DFNSMALL30	P_{PW}	28.91566 S	136.33495 E	79	392
Ingomar – DFNSMALL27	P_{PW}	29.58556 S	135.03865 E	197	480
Nilpena – DFNSMALL42	V	31.02331 S	138.23256 E	112	175

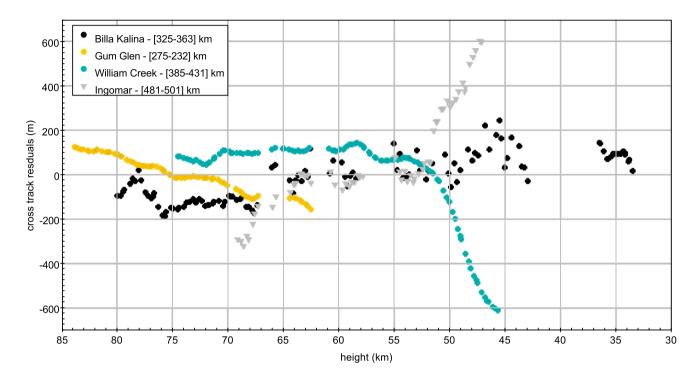


Figure 2. Cross-track residuals of the straight line least squares fit to the trajectory from each view point. These distances correspond to astrometric residuals projected on a perpendicular plane to the line of sight, positive when the line of sight falls above the trajectory solution. The distances in the legend correspond to the observation range [highest point–lowest point]. The Ingomar and William Creek observation residuals start diverging after 52 km altitude, this corresponds to observation angles of about 4° and 5°, respectively.

Glen image is because of the presence of clouds in the direction of the fireball, which efficiently scattered the light from the explosion and subsequently saturated the sensor on a much larger area than for Billa Kalina.

The particle filter method of Sansom et al. (2017) can also be used to put a lower bound on the initial mass of the meteoroid. The near lack of deceleration before the main explosion implies that the mass to cross-section area ratio was large. Using reasonable assumptions on shape (spherical), and density ($\rho = 3500\,\mathrm{kg}~\mathrm{m}^{-3}$, chondiric), we find that the meteoroid was $> 2600\,\mathrm{kg}~(>1.1\,\mathrm{m})$ before impact. We note that this assumes that the meteoroid is a single ablating body before the airbursts (peaks E–G). We know this assumption not to be well founded because some fragmentation happened early on (peaks A and B in Fig. 3), explaining why this number is given as a lower limit.

Using the velocity calculated at the brightest instant on DFN data (peak E in Table 3), and the impact energy measured by the USG sensors (Table 1), we derive a 3400 kg mass for this meteoroid, roughly equivalent to a 1.2 m diameter body, larger than the

Brown et al. (2016) estimate because of a different impact speed used.

The DFN dynamic initial size (>1.1 m) is in good agreement with the USG photometric mass (1.2 m).

The orbit of Kalabity is a typical main belt one with a semimajor axis of 1.80 au (Table 4 and Fig. 4), very different from the HTC type orbit derived from USG data (Table 1).

3.2 DN170630_01 - Baird bay

The Baird Bay meteoroid entered the atmosphere on a very steep trajectory (72° to the horizon), on a trajectory that starts over land in Sceale Bay, and ended in the Southern Ocean $\sim \! 10 \, \mathrm{km}$ West of the Carca Peninsula (Fig. 1). The bolide was visible from 2017-06-30T14:26:41.50 utc (3 min before midnight ACST) for 5.46 s on the DFN camera systems (Table 5). Several eye witnesses reported the bolide, notably from Adelaide, the closest densely populated area, $450 \, \mathrm{km}$ away.

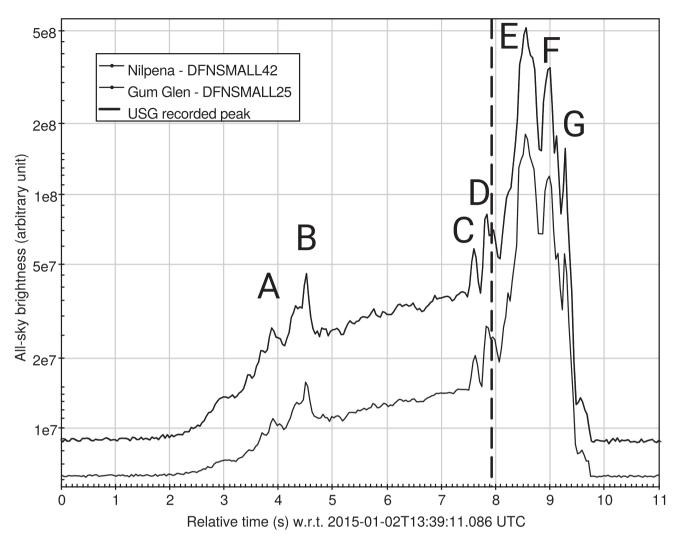


Figure 3. All-sky brightness (sum of all the pixels) from the Kalabity fireball, as recorded with the video cameras at the Gum Glen and Nilpena observatories. Using traditional PSF photometry on star Sirius the light curve is corrected to take into account the effect of autogain. The Nilpena curve has been shifted up for clarity. The peak brightness time recorded by the USG sensors (rounded to the nearest second) is marked by a vertical line.

Table 3. Summary table of bright flight events for DN150102_01 Kalabity. Fragmentation event letters are defined on the light curve (Fig. 3). Times are relative to 2015-01-02T13:39:11.086 UTC. Positions and speeds at the peaks are interpolated from astrometric data.

Event	Time s	Speed ms ⁻¹	Height m	Longitude °E	Latitude °N	Dynamic pressure MPa
Beginning	0.0	15406 ± 79	83317	139.73897	-30.25421	
A	3.90	15351	62586	139.85081	-30.74874	0.05
В	4.50	15320	59453	139.86679	-30.82416	0.08
C	7.61	14487	43432	139.95010	-31.21547	0.52
D	7.83	14272	42571	139.95466	-31.23679	0.57
E - max	8.55	13463	40286	139.96683	-31.29360	0.69
F	8.95	13014	39017	139.97359	-31.32517	0.77
G	9.26	12665	38033	139.97883	-31.34963	0.83
End	10.54	8433	33420	140.00311	-31.46438	

The closest DFN camera is Mount Ive station (190 km away). The Mulgathing camera (250 km directly North from the event) only caught the top of the fireball (Fig. 5), as the image circle is cropped on the short side of the sensor (usually North and South).

Like Kalabity, Baird Bay experienced early fragmentation under pressure <1 MPa (peak A at 0.08 MPa), however a much larger pressure was required to destroy it (peak D, most likely between 1 and 2 MPa).

Table 4. Estimated orbital elements of DN150102_01 Kalabity and DN170630_01 Baird Bay, with 1σ formal uncertainties. (equinox J2000).

Parameter	Unit	DN150102_01 Kalabity	DN170630_01 Baird Bay
Epoch	TDB	2015-01-02T13:39:11	2017-06-30T14:26:41
a	au	1.80 ± 0.02	1.23 ± 0.01
e		0.498 ± 0.006	0.35 ± 0.01
i	0	8.73 ± 0.02	3.57 ± 0.05
ω	0	219.8 ± 0.09	259.06 ± 0.07
Ω	0	281.619 ± 0.001	98.801 ± 0.002
q	au	0.908 ± 0.001	0.805 ± 0.004
Q	au	2.70 ± 0.04	1.66 ± 0.03
α_{g}	0	64.3 ± 0.1	272.14 ± 0.02
	0	51.7 ± 0.2	-12.5 ± 0.1
$\delta_{ m g} \ V_{ m g}$	$\mathrm{m}\mathrm{s}^{-1}$	10776 ± 115	10007 ± 260
$T_{ m J}$		3.89	5.14
α_{inf}	0	70.14 ± 0.02	271.74 ± 0.02
$\delta_{ m inf}$	0	38.05 ± 0.02	-15.89 ± 0.02

Using the same particle technique as in Section 3.1, with a reasonable assumptions on shape (spherical), and density ($\rho = 3500\,\mathrm{kg}\,\mathrm{m}^{-3}$, chondiric), we find that the meteoroid was >9400 kg (>1.7 m) before impact. Using the particle filter we also find that the main mass was $\simeq 7000\,\mathrm{kg}$ when it airburst at 26 km altitude. Unfortunately no astrometric data is available after the airburst, as the only camera close enough to image the bolide at the end, Mount Ive, has a large area of the sensor saturated because of the airburst (peak D in Fig. 6 and Table 6). The video record from the very distant O'Malley camera (410 km) shows that some material was still ablating for at least 0.85 s after the instant of peak brightness. This means that there is a distinct possibility that a main mass survived, and fell in the Southern Ocean, less than 10 km from the coast off Point Labatt.

The USG sensors locate the airburst $\lambda = 134.5^{\circ} \phi = -34.3^{\circ}$ (WGS84) at h = 20 km altitude (Table 1). This position is ~ 100 km off to the South from our calculated entry parameters (Fig. 1).

On the other hand the USG geocentric velocity vector is consistent with our calculation. The radiant solutions are separated by only 0.4° , and the speeds are different only by $0.1 \, \mathrm{km \, s^{-1}}$, in agreement within uncertainties. This implies that even with the wrong position, the orbit calculated from USG data (Table 1) is in agreement with the DFN orbit (Table 4 and Fig. 4).

4 DISCUSSION

4.1 Reliability of USG fireball data

We have compiled in Table 7 how well USG events match independent observations of those events, using data both from the literature and the two fireballs described here.

It is possible to discuss the reliability of the USG data in terms of different desired outcomes.

4.1.1 For orbital studies

The factors that come into play to calculate a meteoroid orbit are the accuracy of the *location*, the absolute *time*, and the geocentric *velocity vector*.

All USG events in Table 7 agree in absolute time with independent records to within a few seconds.

Locations are correct in most cases, except for the Baird Bay event described in this work. However this $\sim 100 \, \text{km}$ location issue in this case is not important for orbit calculation.

Hence the questions lie with the three geocentric Cartesian velocity components. Granvik & Brown (2018) show that in most cases a precision of 0.1 km s⁻¹ on the velocity is good enough for source region analysis, so we do not expect the lack of precision on the USG numbers to be an issue here. An accurate height can be useful to take into account the deceleration in the atmosphere, but it is not essential as we are looking at massive bodies that hardly decelerate before the airburst. Because radiant and speed are less likely to be correlated than the Cartesian velocity components, we have re-projected these velocity components as radiant and speed. The speeds are inconsistent in most cases (Table 7). The worst USG estimates are for the Buzzard Coulee meteorite (18.1 km s⁻¹ calculated by Milley 2010 compared to 12.9 km s⁻¹ USG), and the Romanian bolide (27.8 km s⁻¹ calculated by Borovička et al. 2017 compared to 35.7 km s⁻¹ USG). These were underestimated by 28 per cent, and overestimated by 28 per cent, respectively. The USG radiant vector is off for most events, sometimes by only a couple of degrees (which does not drastically affect the orbit), but sometimes by as much as 90° (Buzzard Coulee and Crawford Bay events). From these considerations, only 4 out of 10 events in Table 7 would have a reasonably accurate orbit if calculated from USG data: 2018 LA, Baird Bay, Chelyabinsk, and Košice. The USG orbits of some meteoroids are even misleadingly peculiar: Kalabity and Romanian would be on unusual HTC orbits (as already noted by Brown et al. 2016).

Therefore USG data can generally not be relied on for orbit determination, and there is no way to know for which events the data are reliable.

4.1.2 For material properties studies

The atmospheric behaviour of a meteoroid can yield some insights on what the meteoroid is made of and how it is held together. If no meteorite is recovered, the small set of USG sensors parameters contains very limited information regarding the rock itself, but it is nevertheless possible to derive the bulk strength of the body. A basic way of achieving this is to look at the dynamic pressure required to destroy the body (using $s = \rho_{\rm atm} v^2$ from Bronshten 1981). This is not a perfect indicator as it does not show subtleties in the rock structure, but it should be able to distinguish iron, chondritic, and cometary material, as these differ in bulk strengths by orders of magnitude. The key parameters are then the *height* of peak brightness (to determine atmospheric density $\rho_{\rm atm}$), and the *speed v*.

As shown by Brown et al. (2016; Table 4), the USG sensors tend to report reasonably accurate heights of peak brightness. We note that most of height inconsistencies are usually due to another peak in the light curve being recorded.

As seen in the previous paragraph, speeds can be wrong by as much as 28 per cent, which induce a factor of 2 error in strength. We conclude that the inaccuracy of USG numbers do not affect strengths by more than an order of magnitude, this is good enough with respect to our original aim.

4.1.3 For size-frequency studies

The USG data have the advantage of using the entire planet as a collector, yielding large sample sizes that ground-based networks

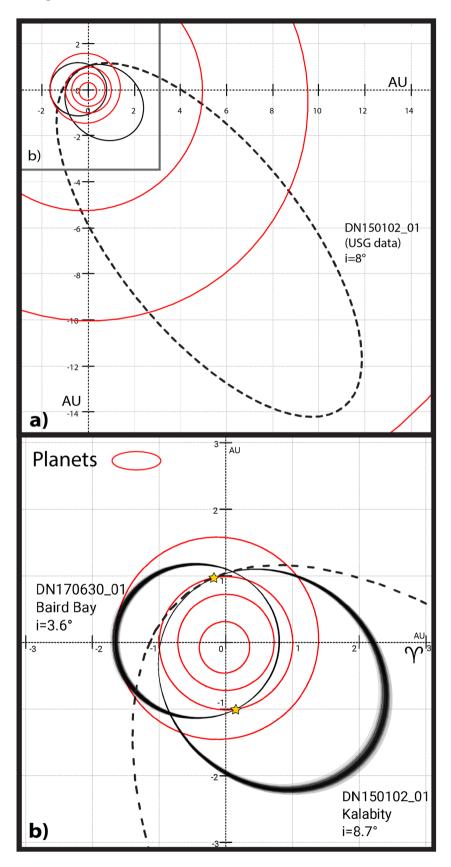


Figure 4. Ecliptic plot of the pre-atmospheric orbit of the Kalabity and Baird Bay meteoroids. **b** is limited to the inner Solar system, while **a** goes out all the way to the orbit of Uranus. The solid lines are orbits using DFN data (the shades of grey in **b** represent the confidence region as calculated by Monte Carlo simulations), whereas the dashed lines are using USG data. The orbit of Baird Bay calculated from USG data is indistinguishable from the DFN one. On the other hand the orbit of Kalabity is very different, mostly because of a speed issue with USG data.

Table 5. Locations and nature of instrumental records DN170630_01. P: Photographic record (long exposure high-resolution image), V: compressed PAL video (25 frames per second). PW and PF designate the de Bruijn encoding method, as described in Section 2.1. Ranges are from the fireball at 70 km altitude. Photographic imaging system was out of order for O'Malley. Note that the Mulgathing camera did not receive the PF firmware update immediately because of a temporary internet connectivity issue.

Observatory	Instruments	Latitude	Longitude	Altitude (m)	Range (km)
Mount Ive – DFNSMALL62	P _{PF}	32.45919 S	136.10332 E	293	201
Days Hill – DFNEXT005	P_{PF}	34.20749 S	138.66151 E	363	439
Nilpena – DFNSMALL12	P_{PF}	31.02328 S	138.23260 E	122	447
Glenrest – DFNSMALL06	P_{PF}	33.01963 S	138.57554 E	722	414
Billa Kalina – DFNSMALL43	P_{PF}	30.23759 S	136.51566 E	113	387
Mulgating – DFNSMALL15	P_{PW}	30.66078 S	134.18608 E	149	274
Woomera – DFNSMALL14	P_{PF}	31.19609 S	136.82682 E	163	329
O'Malley – DFNSMALL40	V	30.50663 S	131.19534 E	117	410

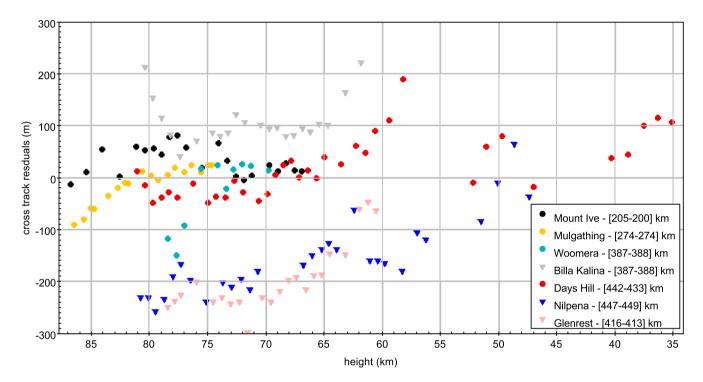


Figure 5. DN170630_01 Baird bay. Cross-track residuals of the straight line least squares fit to the trajectory from each view point. These distances correspond to astrometric residuals projected on a perpendicular plane to the line of sight, positive when the line of sight falls above the trajectory solution. The distances in the legend correspond to the observation range [highest point—lowest point].

will never be able to reach for this class of objects. Hence they can be a good tool for size-frequency studies, provided the *size* of the impacting bodies can be accurately determined, and the *detection efficiency* is well constrained.

As detailed in Section 2.2, using the empirical relation of Brown et al. (2002) and assuming a density, the radiated energy reported by the USG sensors can be converted into mass and size, with the caveat of speed accuracy. The energy estimates seem to match independent observation for the events presented here (Table 7).

As of the detection efficiency, Brown et al. (2002) mentions a 60–80 per cent Earth observation coverage by the USG sensors for their study on 1994–2002 data. If we subset the USG events in two different groups, before and after the study of Brown et al. (2002), we get on average 19 events per year before, and 26–27 events per year after 2002 September. This 40 per cent increase would suggest a 100 per cent Earth coverage after 2002. However it is interesting

to note that the $0.4\,\mathrm{kT}$ impact of $2014\,AA$ (Farnocchia et al. 2016) was not reported by the sensors.

USG data is therefore useful for size frequency studies (like the work done by Brown et al. (2002), Brown et al. (2013), as long as the sub-population grouping is done by other means than by the orbit calculated using the USG velocity data.

4.1.4 For meteorite searching

Although metre-scale impactors are usually too big to be able to decelerate enough before reaching dynamic pressures that destroy them, these objects still have a large chance of surviving as meteorites. We try to assess here the viability of initiating dark flight calculations using a weather model combined the USG entry vector. All the parameters in Table 7 (apart from time) need to be accurate.

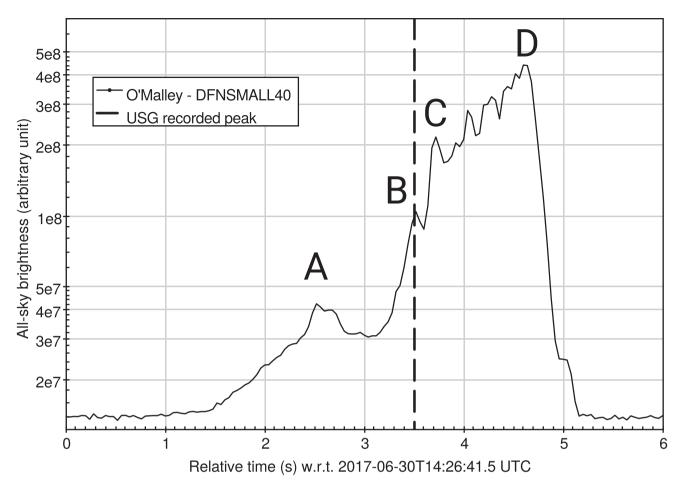


Figure 6. All-sky brightness (sum of all the pixels) from the Baird Bay fireball, as recorded with the video camera at the O'Malley observatory. Using traditional PSF photometry on star α Centauri the light curve is corrected to take into account the effect of autogain. The peak brightness time recorded by the USG sensors (rounded to the nearest second) is marked by a vertical line.

Table 6. Summary table of bright flight events for DN170630_01 Baird Bay. Fragmentation event letters are defined on the light curve (Fig. 6). Times are relative to 2017-06-30T14:26:41.50 UTC. * marks figures that have been extrapolated. The end parameters have not been extrapolated as it is not possible to know what mass is left after the large explosion (peak D), and how this mass decelerated.

Event	Time s	Speed ms ⁻¹	Height m	Longitude °E	Latitude °N	Dynamic pressure MPa
Beginning	0.0	15095 ± 61	86782	134.23858	- 32.99306	
A	2.51	14906	52111	134.21168	-33.08981	0.08
В	3.51	13786	38817	134.20123	-33.12718	0.42
C	3.71	13140	36240	134.19919	-33.13445	0.58
Last astrometric data point	3.80	12783	35181	134.19836	-33.13743	0.65
D – max	4.61	9568*	25648*	134.19083*	- 33.16432*	2.31*
End	5.46					

Although the height of peak brightness is wrong for Chelyabinsk, the reported (*latitude*, *longitude*, *and height*) triplet is located near the ground truth track, hence the fall analysis would not significantly change for large masses. Therefore of the events compiled in Table 7, only two out of nine events (Košice and Chelyabinsk) would have reasonably accurate fall positions if computed from USG records.

But even worse, the 0.1° error on latitude/longitude translates into a $\pm 5\,\mathrm{km}$ error on position on the ground, this is particularly large for undertaking meteorite searching activities.

From these considerations, it would be ill-advised to undertake meteorite searching solely based on USG data.

$\bf 4.2\,$ On the ground-based imaging capabilities of metre-scale impactors

With the help from collaborators outside Australia, the DFN is expanding into the Global Fireball Observatory, and will eventually cover 2 per cent of the Earth surface in the next few years. Metre-scale object will fall on the covered area every 1–2 yr on av-

Table 7. USG events that have their trajectory independently estimated. Note that the date/times of the events all match the independent measurements. The location is considered valid if the (latitude, longitude, height) is somewhere on the trajectory. CSS: Catalina Sky Survey, V: video, P: photographic, PE: photometer, CV: casual video, I: infrasound. ✓: correct within errors. ≈: incorrect, but not far off. X: incorrect. NR-U: not reported by USG. NR-L: not reported or yet published in literature. *: From light curve and infrasound data, [5] conclude that the impact kinetic energy for Košice is >0.1 kT, without an upper limit. References: (0) this work; (1) Hildebrand et al. (2018); (2) Brown et al. (2016); (3) Borovička et al. (2017); (4) Borovička et al. (2013b); (5) Borovička et al. (2013a); (6) Farnocchia et al. (2017); (7) Milley (2010); (8) Jenniskens et al. (2009); (9) Borovička & Charvát (2009); (10) Palotai et al. (2018); (+) JPL Horizons ephemeris service, using CSS and ATLAS astrometry.

Event	Date (UTC)	Instruments	Location	Airburst height	Speed	Radiant	Energy	Ref
2018 LA	2018-06-02T16:44:12	CSS	NR-L	NR-L	✓	✓	NR-L	+
Crawford Bay	2017-09-05T05:11:27	CV, I	\approx	\checkmark	X	Х	✓	1
DN170630 - Baird Bay	2017-06-30T14:26:45	P, V	×	X	\checkmark	\checkmark	\checkmark	0
Dishchii'bikoh	2016-06-02T10:56:32	V, CV	X	NR-U	NR-U	NR-U	\approx	10
Romanian	2015-01-07T01:05:59	CV, PE, P	✓	\approx	X	\approx	✓	2, 3
DN150102 - Kalabity	2015-01-02T13:39:10	P, V	✓	\checkmark	X	Х	✓	0, 2
Chelyabinsk	2013-02-15T03:20:21	CV	\approx	X	\approx	\approx	\checkmark	2, 4
Košice	2010-02-28T22:24:47	V, P, PE	✓	\approx	\checkmark	\approx	√ ∗	2, 5
Buzzard Coulee	2008-11-21T00:26:40	CV	✓	\approx	X	X	NR-L	2, 7
Almahata Sita (2008 TC3)	2008-10-07T02:45:40	CSS	\approx	\checkmark	X	X	\checkmark	2, 6, 8, 9

erage, but is the currently deployed technology fit to observe such events?

4.2.1 Night time observations

Fireball observatories are typically optimized to observe the behaviour of macroscopic meteorite droppers throughout their trajectory during the night. The challenge is mostly a dynamic range one: being sensitive enough to observe the smaller meteoroid at a high altitudes to get precise entry speed for orbit calculation, whilst not saturating the records of larger rocks shining 100 million times brighter when they reach the dense layers of the atmosphere.

So far no iron meteorite fall has been instrumentally observed, but it is expected that this class of objects contains the smallest meteoroids (i.e. the faintest fireball) that can drop a meteorite, as their large strength allows them to enter with limited mass-loss due to fragmentation. For instance, if we assume little to no gross fragmentation (Revelle & Ceplecha 1994), to produce a 100 g meteorite the parent meteoroid ($\rho = 7900 \, \mathrm{kg \ m^{-3}}$) can be as small as 0.5 kg $\equiv 5 \, \mathrm{cm}$ diameter, assuming the most favourable entry conditions (vertical entry at $12 \, \mathrm{km \, s^{-1}}$). It is desirable to observe the meteor before the rock starts being affected by the atmosphere too much, 80 km altitude at which it would glow at magnitude $M_{\rm V} = -1.5$ (assuming a luminous efficiency of 0.05).

On the bright end, we look at the compilation of Borovička et al. (2015) and see that metre-scale events usually approach $M_{\rm V}^{\rm max} = -18$, although this is highly dependent on their atmospheric behaviour, where and how important the fragmentation events are.

The set goal is then to have instruments that can cover 20 stellar magnitudes of effective dynamic range.

Long exposure high-resolution fireball camera systems have a long track record for yielding meteorite ground locations and orbits (listed as 'dedicated search from detailed computation of trajectory' by Borovička et al. 2015), compared to video systems. Thanks to their logarithmic response, film based imagers cover a very wide dynamic range (~15 stellar magnitudes), but those systems are costly and impractical for large distributed autonomous fireball networks (Howie et al. 2017a), and do not achieve the 0 magnitude sensitivity objective. The DFN (Howie et al. 2017a) and the European Network (Spurný et al. 2016) have recently switched from film to digital camera technology. This shift has simplified some operational aspects (e.g. enhanced autonomy, better reliability, eased

data reduction), but it has come at the cost of a much limited dynamic range: ~ 8 magnitudes without saturation. For astrometric purposes this range can be extended to 15 magnitudes (Devillepoix et al. 2018), but this is still quite far from the 20 magnitudes objective.

Video cameras are generally more sensitive than the still imagers, but suffer from the same limited dynamic range. Although a lot of events have been recorded, fixed frame rate TV systems have not been proficient in yielding meteorite fall positions. This is likely to be due to the low resolution offered by those systems (a PAL video system with a matching circular fisheye lens has an average pixel size over $10 \times \text{larger}$ than the DFN cameras), and the difficulty of getting enough stars for astrometric calibration across the field of view (most of these cameras cannot shoot long exposures). However recent advances in digital video camera technology allow higher resolutions, long exposures for calibration, and higher bit depth, so we expect networks based on these systems to be more successful at meteorite recovery in the near future (e.g. the Fireball Recovery and InterPlanetary Observation Network (*FRIPON*) network of Colas et al. 2015).

4.2.2 Daytime observations

The easy exposure control on industrial digital cameras allows low-noise long exposure calibration shot to be taken at night, but also permits very short exposures to operate during the day. The *FRIPON* network endeavours to operate their cameras during both night time and daytime (Audureau et al. 2014), however fireball detection on daytime frames appears somewhat challenging (Egal et al. 2016). Even if calculating fall positions turns out to be difficult from daytime data, the prospects of being able to calculate orbits for meteorites that have been independently recovered are very interesting (9 out of 14 US meteorite falls in the last 10 yr do not have a trajectory solution published), as the astrometric calibration of casual footage can be very time consuming.

5 CONCLUSIONS

This work investigates the NEO impacting population around the metre-scale size range. Such events are relatively rare (35–40 per year), therefore a large collecting area is crucial in order to study them. The DFN is leading the effort as a ground-based instrument, covering over 3 million km².

5178 H. A. R. Devillepoix et al.

Meteoroids that have been observed by both the USG sensors and independent means comprises a small set of nine events. In this study we use a precise comparison of these events to assess the reliability of the USG sensors for NEO studies, yielding the following unequivocal conclusions:

- (i) USG sensors data are generally unreliable for orbit calculations. The new metre-scale impactors source region of Brown et al. (2016; HTC) is based on three particular USG meteoroid orbits. We have shown that two of these are erroneous, seriously questioning the existence of this source region.
- (ii) Size frequency distribution work relies on determining rough sizes and having a good knowledge of the probing time area. The USG seem to achieve both with reasonably good precision. This confirms the sound basis of the work done by Brown et al. (2002) and Brown et al. (2013).
- (iii) Basic impactor physical properties (size and strength) can be well constrained with USG data. This validates the conclusions of Brown et al. (2016) that relate to physical properties of objects.
- (iv) Based on how often the derived trajectories are wrong, it would be naive to invest large amounts of resources to undertake meteorite searching using USG data.

We also note that ground-based fireball networks must find solutions to increase the dynamic range of their observations, in order to get sound observation data when metre-scale objects impact the atmosphere.

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